

## Optimized Battery Charging System for Electric Vehicle with Proportional Integral Controlled High Frequency Resonant Bridgeless Power Factor Correction Converter

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### Abstract:

The goal of research is to develop an optimized Electric Vehicle (EV) charging system with enhanced efficiency and cost-effectiveness by integrating a High Frequency Resonant Bridgeless (HFRB) Power Factor Correction (PFC) converter and a Proportional Integral (PI) controller. To attain the goals, the subsequent tasks are proficient: a novel Bridgeless PFC converter is developed to improve power factor correction and power quality; a PI controller is exploited to control output voltage with reduced implementation and maintenance costs and a Pulse Width Modulation (PWM) generator within a Hysteresis Current Controller (HCC) is deployed to enhance current protection, system stability, and fault tolerance. The system is validated using MATLAB/Simulink-based simulations. The significant outcomes are the accomplishment of a high charging efficiency of 97%, improved power quality, reduced heat generation, and enhanced system control operations. The significance of obtained results is that the proposed system ensures optimized EV battery charging with increased reliability, reduced implementation costs, and robust fault tolerance, contributing to the development of effective EV charging infrastructure.

## Keywords:

EV, HFRB-PFC converter, PI, PWM and Hysteresis Current Controller (HCC)

## Notation List

|                       |   |
|-----------------------|---|
| $V_S$                 | Input voltage                             |
| $f_L$                 | AC line frequency                         |
| $V_O$                 | Output voltage                            |
| $V_{O1}$ and $V_{O2}$ | Voltage across $V_{C1}$ and $V_{C2}$      |
| $k$                   | Resonant inductors ratio                  |
| $G$                   | Voltage gain                              |
| $f_S$                 | Switching frequency                       |
| $\hat{V}_S$           | Highest value of sinusoidal input voltage |
| $i_{error}$           | Current error                             |
| $i_{Aref}$            | Reference current                         |
| $i_A$                 | Measured current                          |

## 1. Introduction

In recent days, large number of EV's are undergoing various developments in order to attain enhanced EV charging performance [1-2]. However, attaining better EV charging still faces certain difficulties associated with the higher requirements of power quality for EV charging [3-4]. Several measures utilized, obtained AC power from the source, rectified using uncontrolled rectifier bridge and fed directly to the EV charging load, thereby leading to reduced power factor within the charging system [5-6]. Thus, reduced power factor leads to increased harmonic distortion in current [7-8]. In spite of this, to address this issue and to obtain improved, convenient and timely charging of EV battery, PFC plays as essential role [9-10].

In conventional PFC converter, semiconductor device causes certain conduction losses, thus to reduce these conduction losses, bridge rectifier plays a crucial part at the input phase, thus increasing the system efficiency [11-12]. The integration PFC enables to acquire filtering and rectification of the obtained AC power by providing power factor correction [13].

However, due to larger power requirements of the EV battery, during insufficient voltage and high current supply, Rectifier Bridge undergoes higher loss which cannot be easily ignored [14-15-16]. Henceforth, various PFC approaches are considered to attain improved EV battery charging. Initially, Bridgeless – Boost converters are considered due to its simple and easy integration. However, these converters struggled with reduced voltage output. In [17] the authors innovated PFC converter and it attains reduced switching losses with upgraded power quality, thus improving the overall efficacy of the PFC but struggled with reduced efficiency during low power circumstances.

Significantly, authors in [18] introduced Buck-Boost PFC AC-DC converter for attaining control of battery charger for low voltage EV. Nevertheless, it increases the system complexity. In addition to this, [19] utilizes a discontinuous Current Conduction Mode (DCM) BL PFC converter for attaining natural PFC for AC input. The implementation of DCM with PFC protects the input voltage and current, providing reliable and robust converter performance. Nonetheless, this technique is not suitable for larger EV applications as it provides reduced efficiency during high power situations.

Henceforth, this paper suggests a High Frequency Resonant Bridgeless PFC converter for overcoming above mentioned shortcomings and to attain effective charging of EV. The foremost framework and objectives are,

- To attain enhanced power factor correction and power quality output for effective EV charging, High Frequency Resonant Bridgeless PFC converter is deployed.
- To ensure improved current security with enhanced fault tolerance, PWM generator with HCC is utilized, which increases the system reliability.

- To regulate the output voltage, PI controller is implemented which attains easy and simple integration with reduced expenses providing efficient and reliable control approach.

## 2. Proposed Modelling

Fig. 1 illustrates block diagram of optimized Battery Charging System for EVs. The major objective of this system is to attain high-frequency power conversion for improved charging of EV.

Initially, input AC supply is fed to high frequency resonant bridgeless PFC converter which enables power factor correction. Power factor correction is achieved by affiliating input current with input voltage, minimising power losses attaining seamless conversion of AC to DC making it suitable for EV charging.

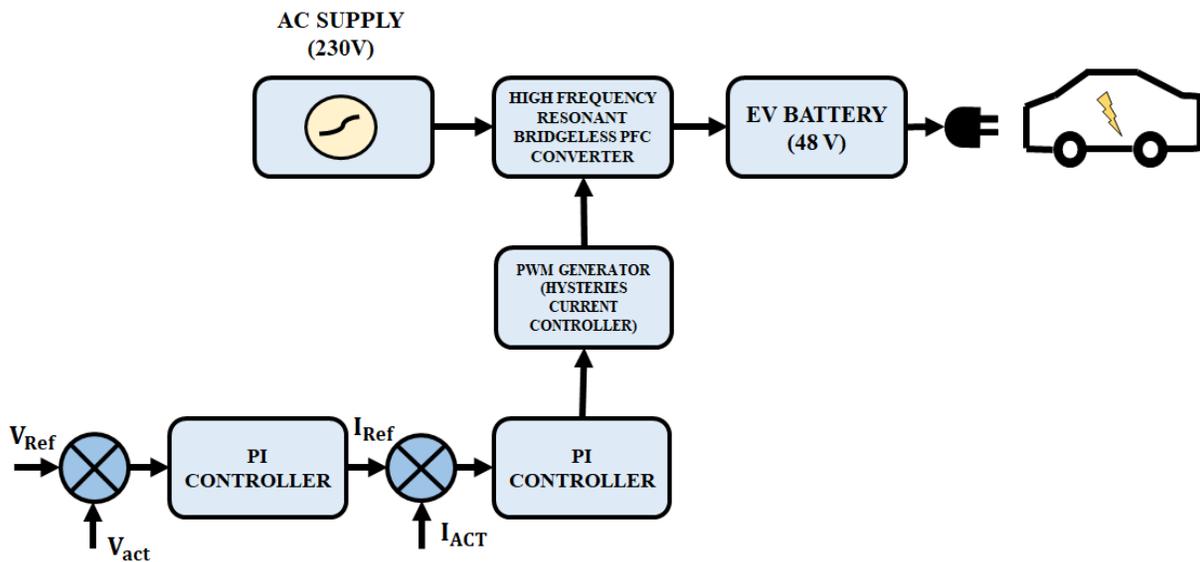


Fig. 1. Block Diagram of Optimized Battery Charging System for EVs

In addition to this, for enhanced PFC converter performance, PWM generator with hysteresis controller and PI controller is utilized. Secondly, PWM generator produces switching pulses for controlling PFC converter, attaining effective and regulated output voltage and current. Furthermore, PI controller, compares the reference voltage with actual voltage and adjust PWM generator consequently. Finally, the output from PFC converter is directly fed to EV for charging. Therefore, the proposed system as a whole ensures to attain optimized EV charging with increased reliability and stability.

## 2-1- Modelling of high frequency resonant bridgeless PFC converter

Circuit of resonant PFC converter is depicted in Fig. 2, input voltage together with LC filter is termed as  $V_s$ . In this approach, switch  $S_1$  with diode  $D_1$  and  $D_{o1}$  is kept ON in the positive half cycle. Similarly, in negative half cycle,  $D_2$  and  $D_{o2}$  is activated. In order to prevent, system short circuit due to input voltage source, external series of diode is considered essential for switch  $S_1$  and  $S_2$ . Henceforth, the gating signals for both switches are applied concurrently without utilizing any sensors for sensing positive and negative half cycles.

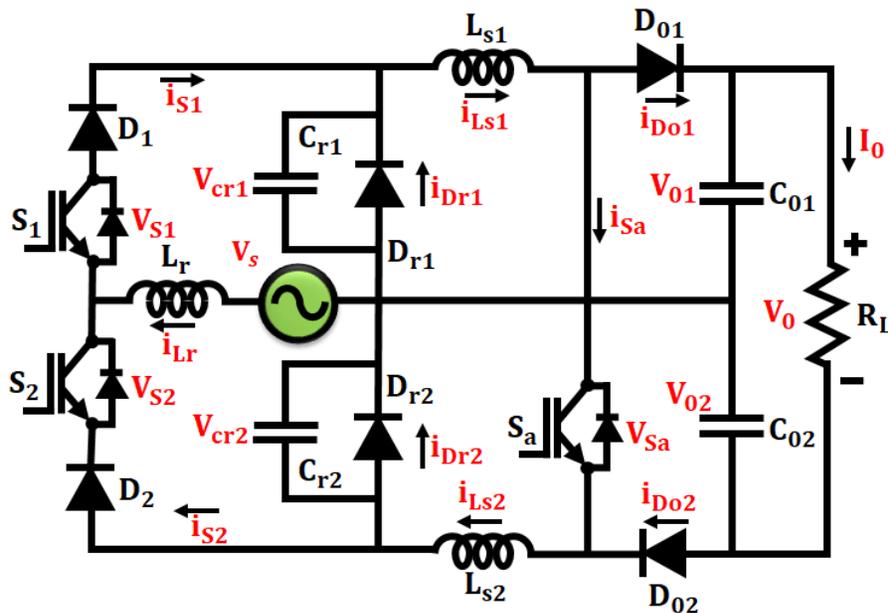


Fig. 2. Circuit Diagram of high frequency BL-PFC converter

In the positive half cycle, converter acts in 2 different modes, mode A, where the input voltage  $V_s$  is higher than that of  $V_o / 2$ . Significantly, during mode B,  $V_s$  is lightly lesser than  $V_o / 2$ , thus, energy transmission is blocked and null crossing distortion is attained at the input current because of gathered energy on  $C_1$ . Due to this reason,  $S_a$  is kept in ON state, hence, the collected energy is transferred to output resonant inductors  $L_1$  and  $L_2$ . Afterwards, this energy is discharged by turning OFF  $S_a$  and Fig. 3 showcases the switching waveform of both stages.

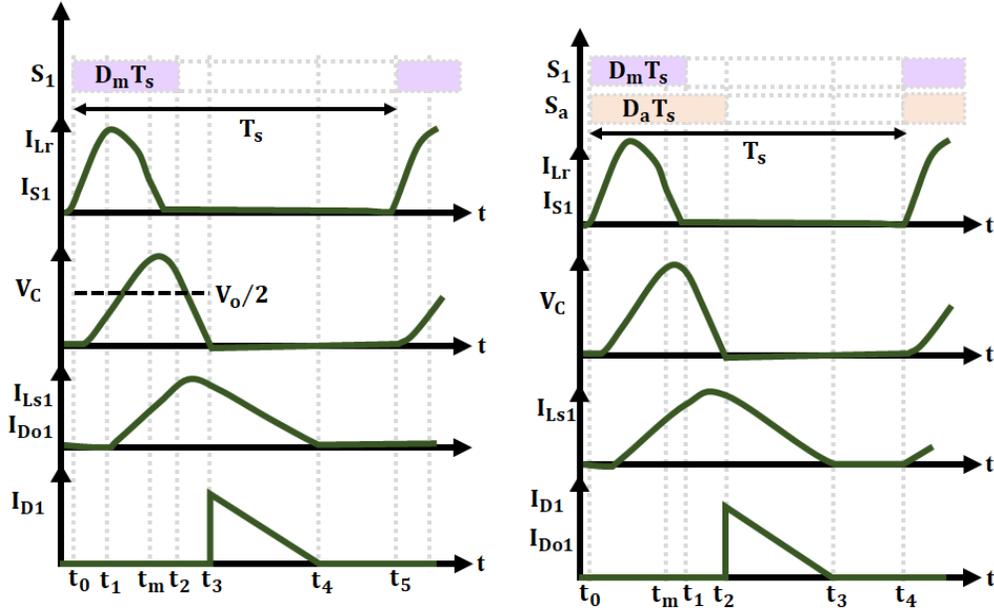


Fig. 3. Switching Waveforms (a) Mode A (b) Mode B

### Operating Modes:

For positive half cycle,  $f_s$  is higher than  $f_L$ . Henceforth,  $V_s$  attains consistent switching cycle. Similarly, the voltage on output side is also regarded as stable as  $C_{o1}$  and  $C_{o2}$  are significantly larger. Due to the symmetrical structure,  $V_{o1} = V_{o2} = V_o / 2$ ,  $C_1 = C_2$  and  $L_1 = L_2 = L_s$ . Where, the voltage across  $V_{C1}$  and  $V_{C2}$  are  $V_{o1}$  and  $V_{o2}$ .

To further, simplify working modes equations,  $k$  and  $G$  is expressed as,

$$k = \frac{L_s}{L_r} \quad (1)$$

$$G = \frac{V_o}{2\hat{V}_s} \quad (2)$$

Where,  $\hat{V}_s$  represents the sinusoidal input voltage's highest value.

$$V_s = \hat{V}_s \sin[\omega_g t] \quad (3)$$

**Operating mode A:** During this mode, switch  $S_a$  is turned OFF, and mode A is further divided into five different time intervals.

**Interval 1:** At  $t_0$ ,  $S_1$  is kept in ON condition, thus  $C_1$  gets charged via  $V_s$ . Whereas,  $C_{o1}$  and  $C_{o2}$  provides energy to  $R_L$ .

$$V_{Cr1}(t) = V_C(t) = \hat{V}_s (1 - \cos[\omega_{r1}(t - t_0)]) \quad (4)$$

$$I_{Lr}(t) = \frac{\hat{V}_s}{Z_{r1}} \sin[\omega_{r1}(t - t_0)] \quad (5)$$

Here,  $\omega_{r1} = 2\pi/T_{r1} = 1/\sqrt{L_r \cdot C}$  and  $Z_{r1} = \sqrt{L_r \cdot C}$ . At  $t_1$ ,  $V_{C1}$  reaches  $V_o/2$ , hence,  $I_{Lr}$  during  $t_1$  is,

$$I_{Lr}(t) = I_1 = \frac{\hat{V}_s}{Z_{r1}} \sqrt{G(2-G)} \quad (6)$$

Where,

$$t_1 = t_0 + \frac{1}{\omega_{r1}} (\pi - \cos^{-1}[G-1]) \quad (7)$$

Where, the voltage and current across  $C_{r1}$  and  $C_r$  are  $V_{Cr}$  and  $I_{Cr}$ . By solving the capacitor voltage charging expression for  $t_1$  at  $V_{C1}$  is similar to half of  $V_o$ , the equation(7) is obtained.

**Interval 2:** During this interval,  $D_{o1}$  is turned ON which in turn produces a resonant loop consisting  $L_1$  and  $C_1$ . Here,  $C_1$  gets charged using  $t_1$  to  $t_m$ . Later,  $C_1$  energy is transferred to  $R_L$  during  $t_m$  to  $t_2$  through  $L_{s1}$ .

**Interval 3:**  $S_1$  is kept OFF, while  $C_1$  releases into load in resonant manner, which continues until  $V_{C1}$  becomes zero and  $D_1$  gets turned ON.

**Interval 4:** At  $t_3$ ,  $D_1$  is kept in ON state and  $V_o/2$  positioned across  $L_1$ , hence, current is minimized linearly.

**Interval 5:** At  $t_4$ , all the semiconductors are turned OFF, thus,  $C_{o1}$  and  $C_{o2}$  provide the load and, the positive cycle ends and the negative cycle begins. Fig. 4 depicts the various working modes of proposed converter.

**Operating mode B:** To balance input current's zero distortion, gating signal  $S_a$  is applied. Furthermore, functioning mode B is again divided into four different intervals and are operate in similar manner of operating mode A. To further attain improved current control with rapid response rate, PWM generator in HCC is utilized. The integration of PWM in HCC achieves enhanced efficiency and reliability with rapid dynamic response rate.

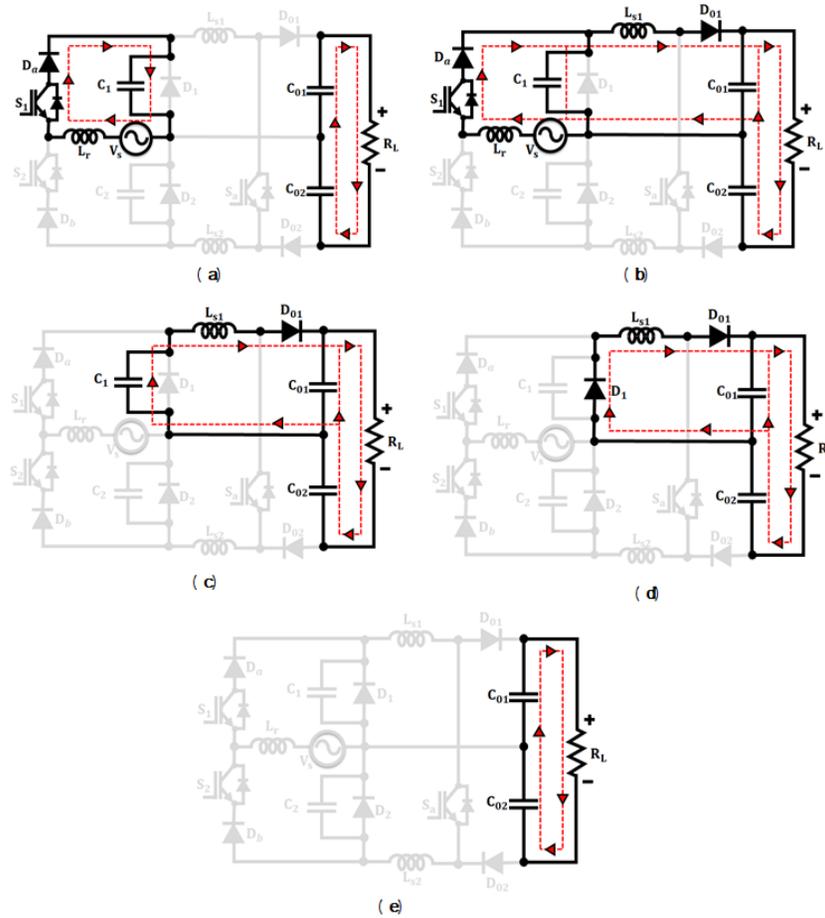


Fig. 4. Circuit Diagram of five intervals in operating mode A with S is inactive

## 2-2- Modelling of PWM generator in HCC

The HCC approach is vitally utilized due to its simplicity, enhanced current defence, quick dynamic response and increased tolerance towards parameter variations. The block of hysteresis current control in illustrated in Fig. 5.

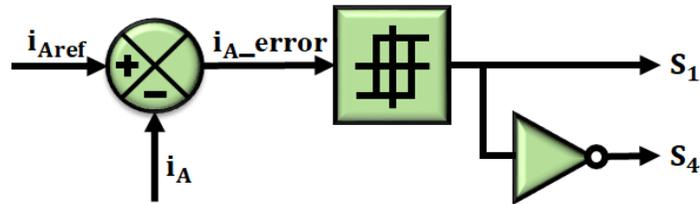


Fig. 5. Block diagram of HCC [20]

The current error ( $i_{error}$ ) is designed by deducting ( $i_{Aref}$ ) and ( $i_A$ ). The obtained error is further compared to the hysteresis band to produce the switching pulses. The hysteresis control constrains current in band and bandwidth value ( $h$ ) is kept stable. The current error is determined using,

$$i_{A\_error} = i_{Aref} - i_A \quad (8)$$

The lower and upper hysteresis band is compared using the hysteresis current controller,

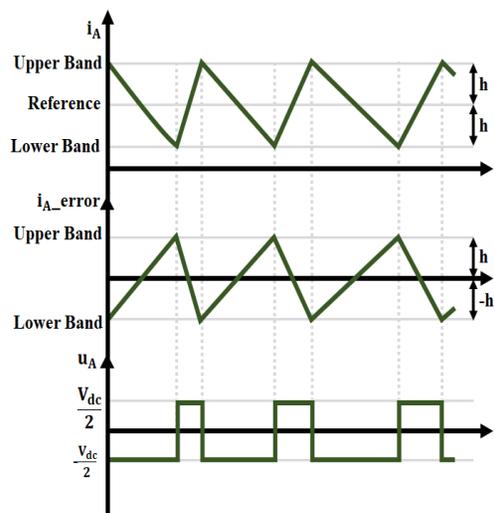


Fig. 6. PWM generation in HCC [20]

If  $i_{A\_error} > +h$  then,  $i_A$  increases and if  $i_{A\_error} < -h$  then,  $i_A$  decreases, the hysteresis current control along with the PWM generation is shown in Fig. 6. Moreover, PI controller is deployed to improve the control performance by removing steady state errors, thus increasing the system stability.

### 2-3- Modelling of PI controller

PI controller is often utilized for rectifying the errors acquired between actual and desired value of developed system. PI controller is the combination of proportional and integral controller which is utilized generally in control system for consistently altering the output based on error signal. Transfer Function of PI controller is evaluated using,

$$G_{PI}(s) = K_p + \frac{K_i}{s} \quad (9)$$

Where,  $K_p$  represents the proportional constant and  $K_i$  denotes integral constant. Fig. 7 represents PI controller's equivalent circuit.

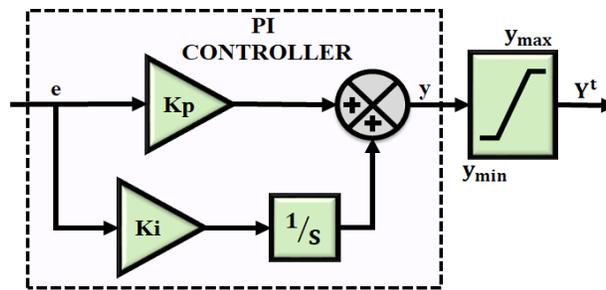


Fig. 7. Equivalent circuit diagram of PI controller [21]

The output generated by the PI controller is expressed as,

$$u(t) = K_p e(t) + K_i \int e(t) dt \quad (10)$$

Where,  $e(t)$  denotes the error signal. Overall, the developed system ensures to attain improved battery charging with optimum control.

### 3. Results and Discussion

This part deals with evaluation and analysis of PI controlled high frequency resonant BL PFC converter using MATLAB/Simulink along with their comparative analysis discussed in terms of their power factor and efficiency. The specification of parameters are added in Table 1.

Table 1. Specification of parameters

| Parameter                              | Specification |
|--|---------------|
| <b>AC Source</b>                       |               |
| Source current                         | 20 A          |
| Source voltage                         | 220 V         |
| <b>high frequency BL-PFC converter</b> |               |
| $L_{S1}, L_{S2}$                       | 4.7 mH        |
| $C_1, C_2$                             | 22 $\mu$ F    |
| $C_{01}, C_{02}$                       | 2200 $\mu$ F  |
| Switching Frequency                    | 10 kHz        |

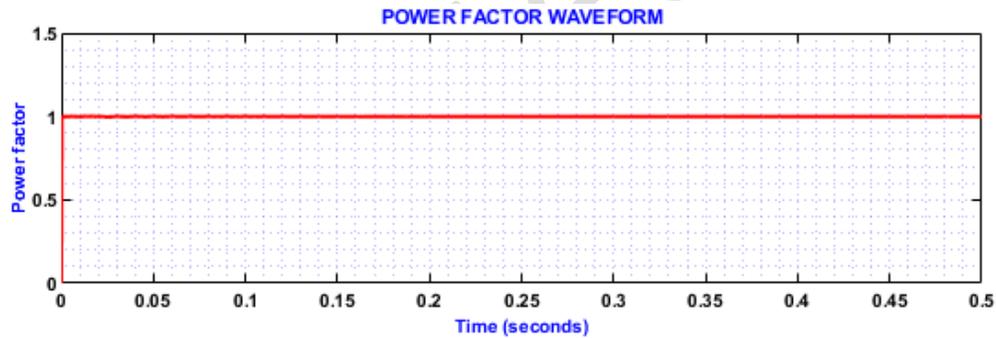


Fig. 8. Waveform of Power Factor

Fig. 8 represents the power factor waveform, in which power factor remains stable at 1 (unity) throughout the entire time period. Indicating, efficient functioning of developed system with reduced power losses and minimized overheating issues.

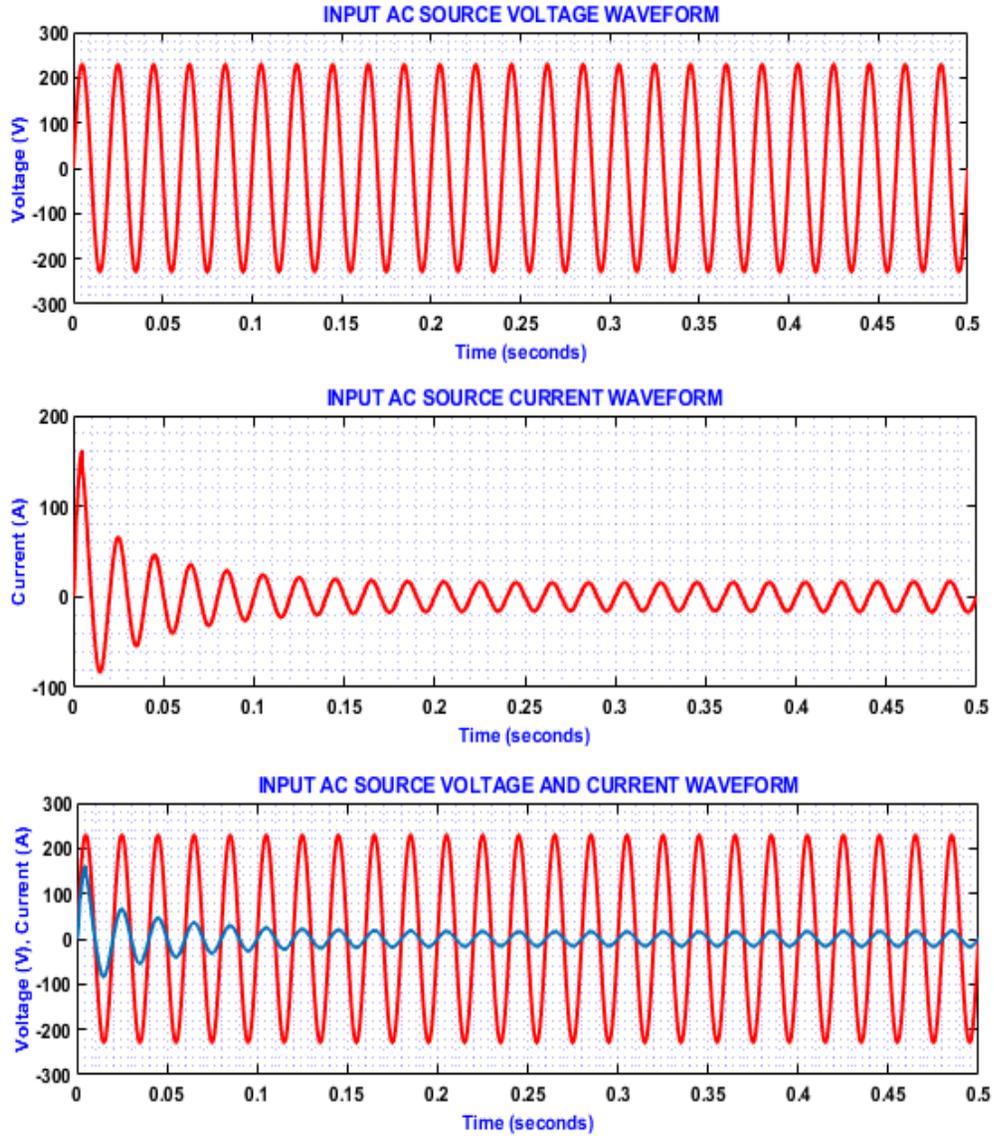


Fig. 9. Waveform of Input AC source Current and Voltage

Fig. 9, the first graph implies the input AC source voltage waveform, where the input voltage remains stable between  $\pm 220$  V, thus ensuring reliable and consistent power supply. Similarly, second graph indicates the input AC source current waveform, in which current initially fluctuates and then stays stable, thereby, enhancing system efficiency. The third graph refers to both voltage and current waveform, where both the current and voltage exhibit perfect synchronization, hence providing effective utilization of real power with reduced reactive power.

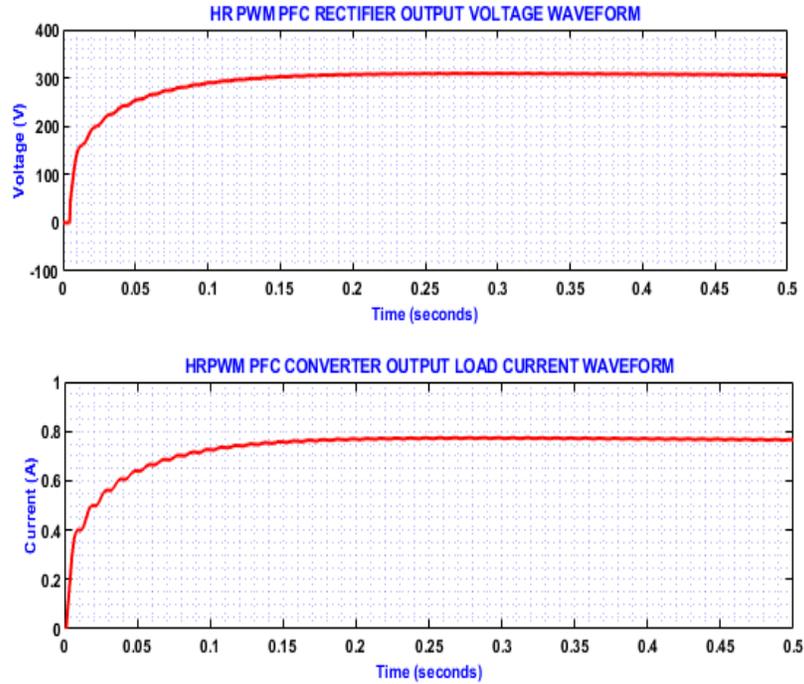


Fig. 10. Rectifier output voltage and converter current Waveform

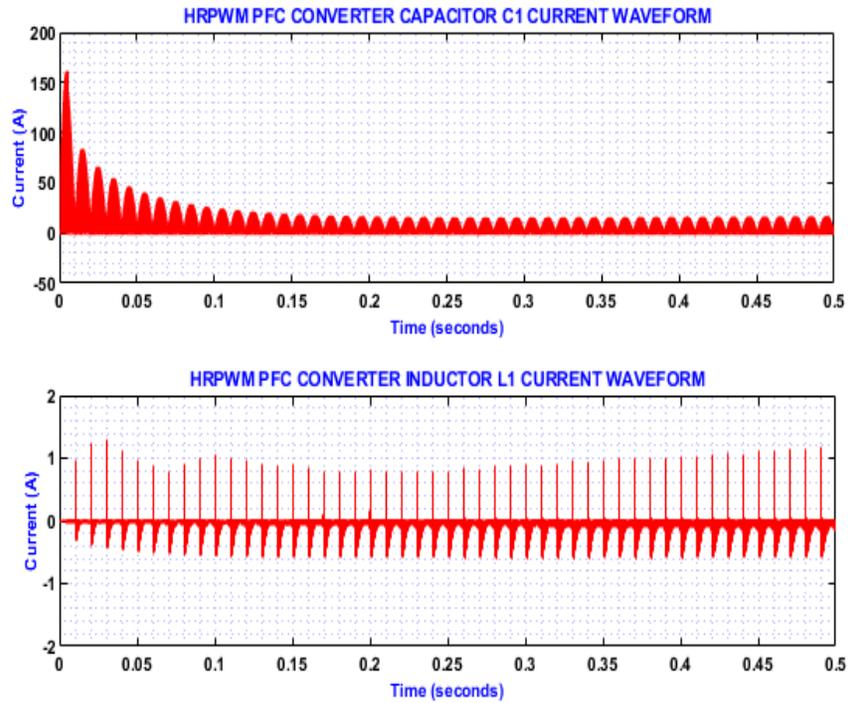


Fig. 11. Converter capacitor current and converter inductor current waveform

Fig. 10 represents the HR PWM PFC rectifier output voltage waveform and HR PWM PFC converter output load current waveform, where both the output voltage and current gradually increases and further stays stable at 300V and 0.7 A respectively. Fig. 11 implies the current waveform for HR PWM PFC converter through capacitor  $C_1$  and inductor  $L_1$ , the first graph represents that, rapid increase in current which further stabilizes through the given time duration. Similarly, the second graph indicates that, the current through inductor initially fluctuates and later stays consistent indicating effective system functioning. The output power of 150 W is attained by this converter.

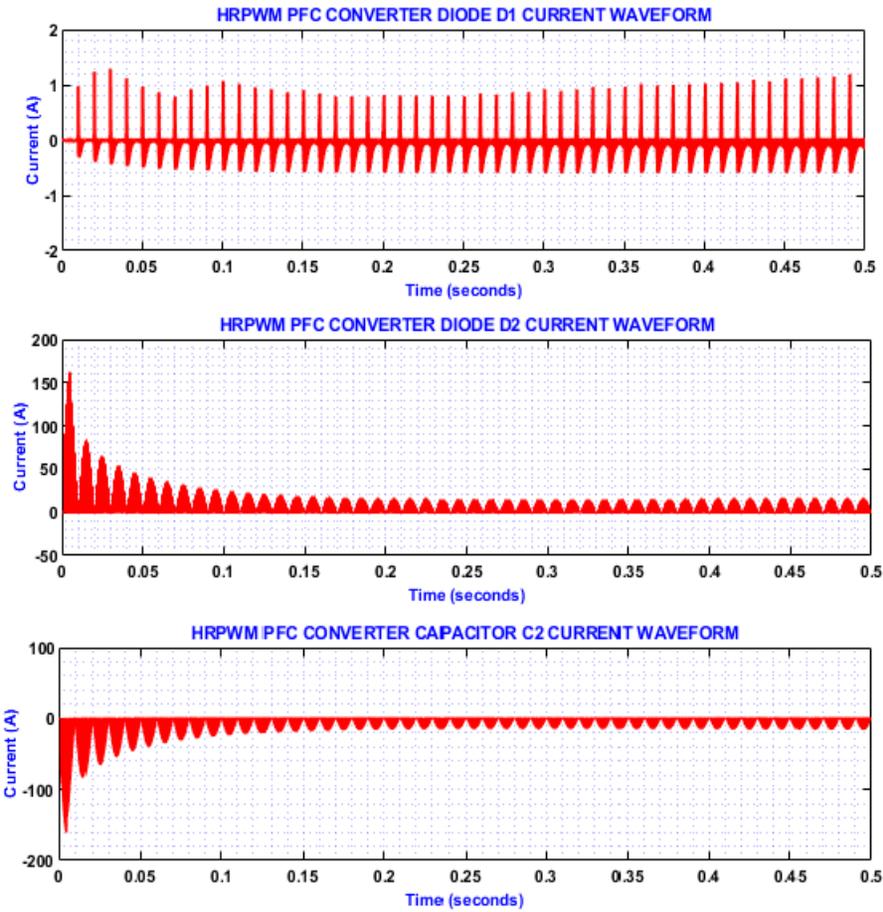


Fig. 12. Converter diode current and capacitor current waveform

Fig. 12 represents three graph comprising HR PWM PFC converter diode  $D_1$ ,  $D_2$  and capacitor  $C_2$  current waveform. The current through diode  $D_1$  keeps deviating while, the current through diode  $D_2$  initially

rapidly increase and further stabilizes. Moreover, current through capacitor  $C_2$  implies that, stable current thus, indicating enhanced system reliability.

### Case 1 → Input Voltage – 220 V

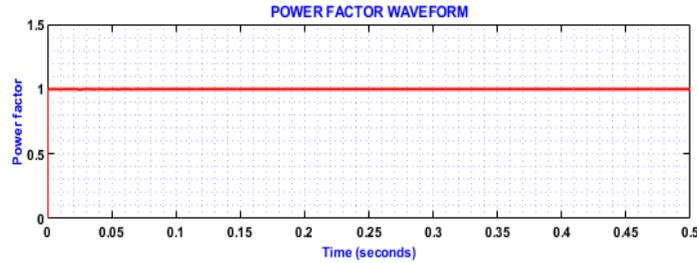


Fig. 13. Waveform for Power Factor

Fig. 13 indicates the waveform of power factor in which the power factor remains at 1 unity throughout the given time duration even with input power 220V, indicating effective system performance with varying input voltage.

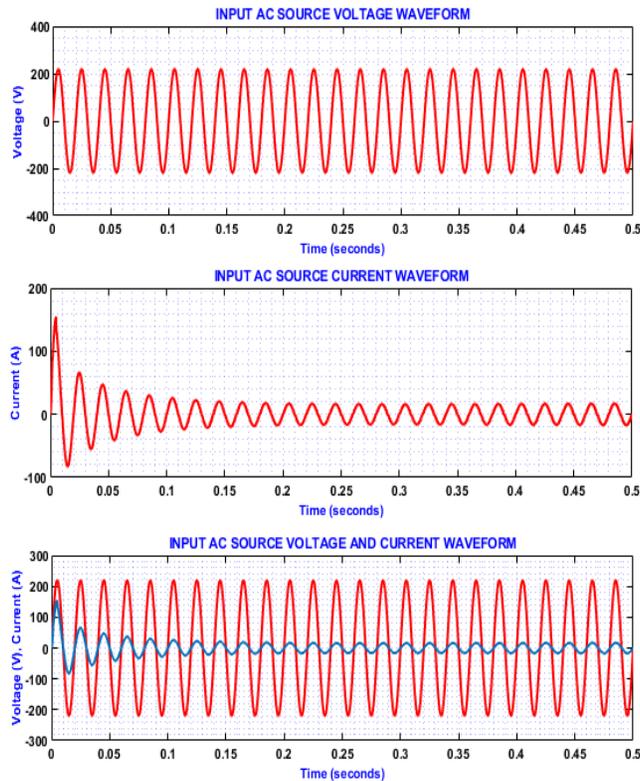


Fig. 14. Waveform of AC source current and voltage

Fig. 14 implies the AC source current and voltage waveform, where voltage remains consistent between  $\pm 200\text{V}$  and current waveform showcases that, current initially fluctuates and steadied. Significantly, third graph depicts that, faultless synchronization of voltage and current.

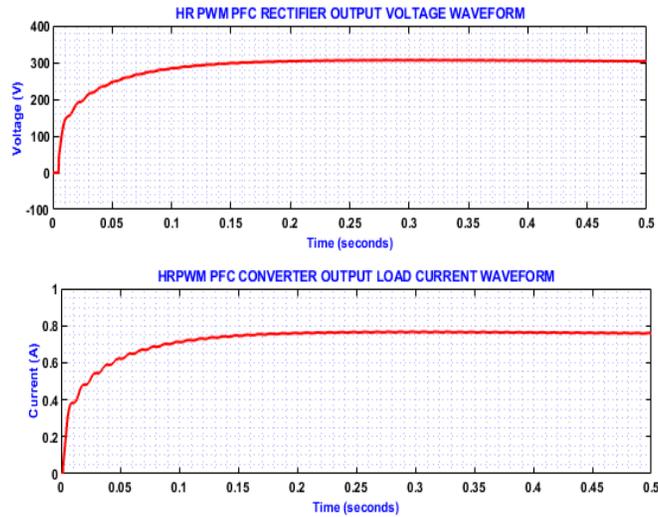


Fig. 15. Waveform for HR PWM PFC converter output current and voltage

Fig. 15 represents the HR PWM PFC converter's output current and voltage, wherever both voltage and current progressively increases and after 0.2 seconds stays consistent throughout the time period.

### Case 2 $\rightarrow$ Input Voltage – 210 V

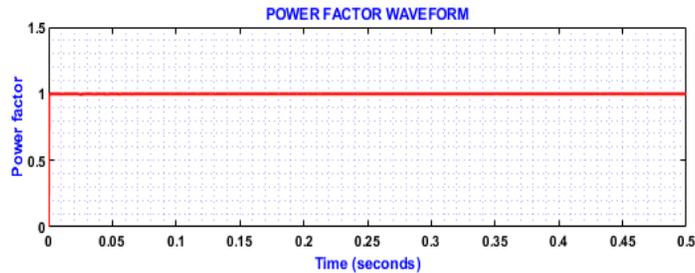


Fig. 16. Power factor

Fig. 16 indicates the power factor, which is fixed at 1 unity even with varying input voltage 210V, thereby, ensuring improved and reliable system performance.

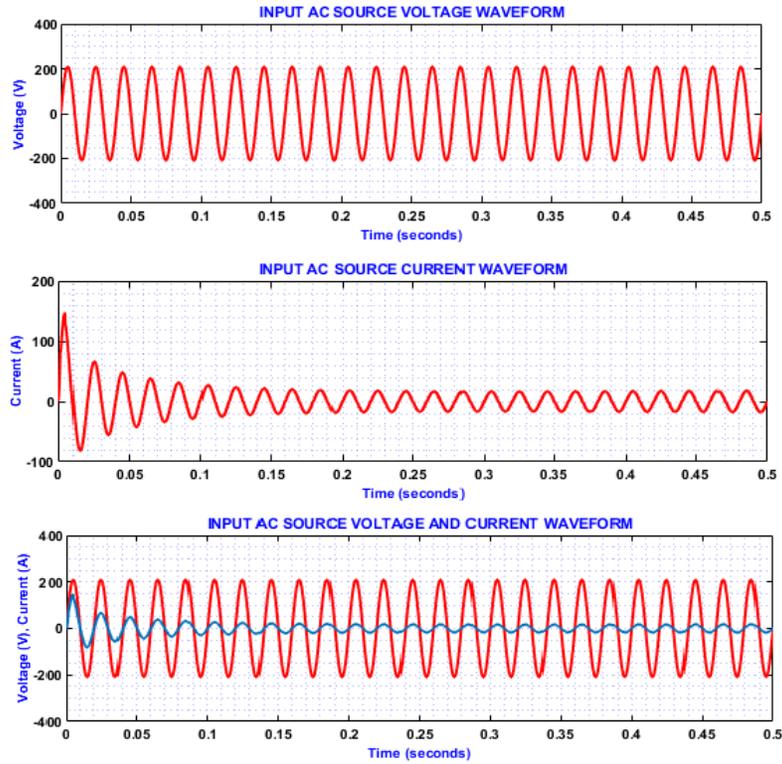


Fig. 17. AC source input voltage and current

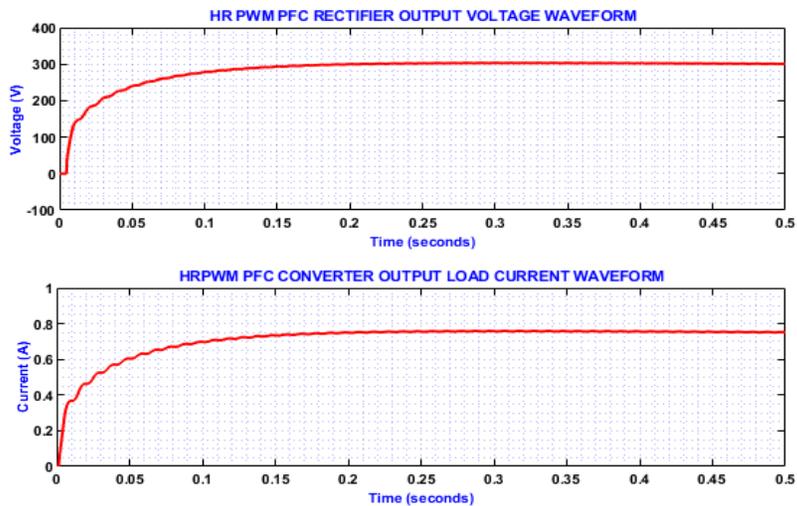


Fig. 18. HR PWM PFC converter output voltage and current

Fig. 17 implies the AC source input voltage and current, where input voltage is fixed at  $\pm 200\text{V}$  and current initially fluctuates and later stabilizes into steady waves. Whereas, the third graph showcases, the alignment of voltage and current, indicating unity power factor.

Fig. 18 indicates HR PWM PFC rectifier voltage on output side and converter current waveform, where the output voltage and current together progressively raises and further stabilizes after 0.2 seconds. In which the first graph displays output voltage at 300 V and the second graph shows output current at 0.7 A respectively.

**Case 3 → Input Voltage – 200 V**

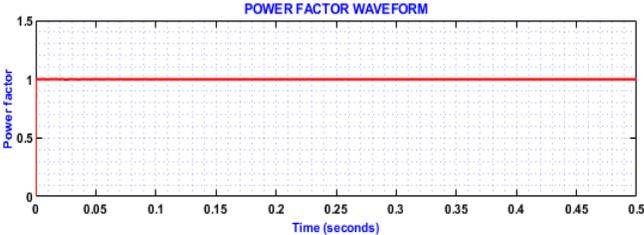


Fig. 19. Power Factor waveform

Fig. 19 represents the waveform for power factor which is fixed at 1, indicating a unity power factor throughout the given time duration even under varying input voltage 200V. Unity power factor refers that leads to reduced reactive power, indicating enhanced system functioning.

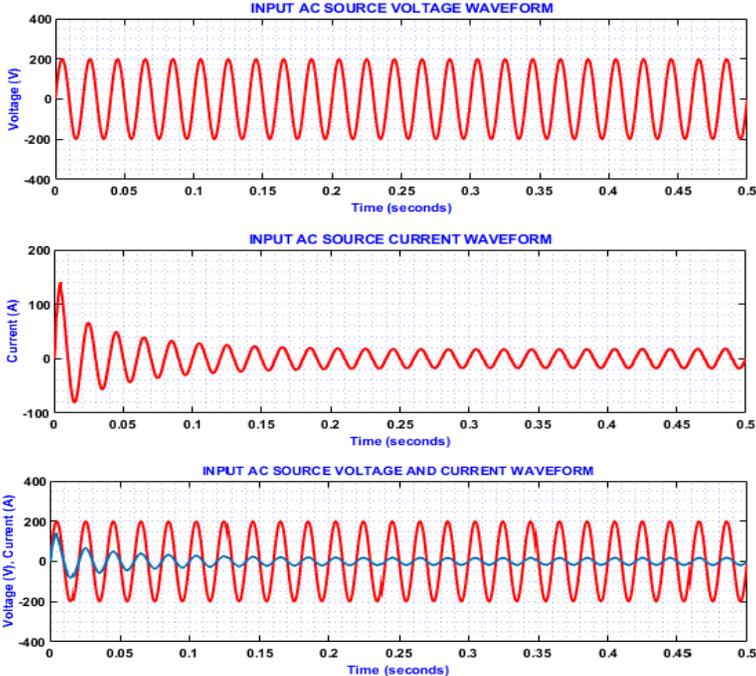


Fig. 20. Waveform of Input AC source

Fig. 20 suggests the waveform for input voltage and current where, both input voltage and current remains stable and consistent for the depicted time duration and the third chart displays the combined form of both voltage and current.

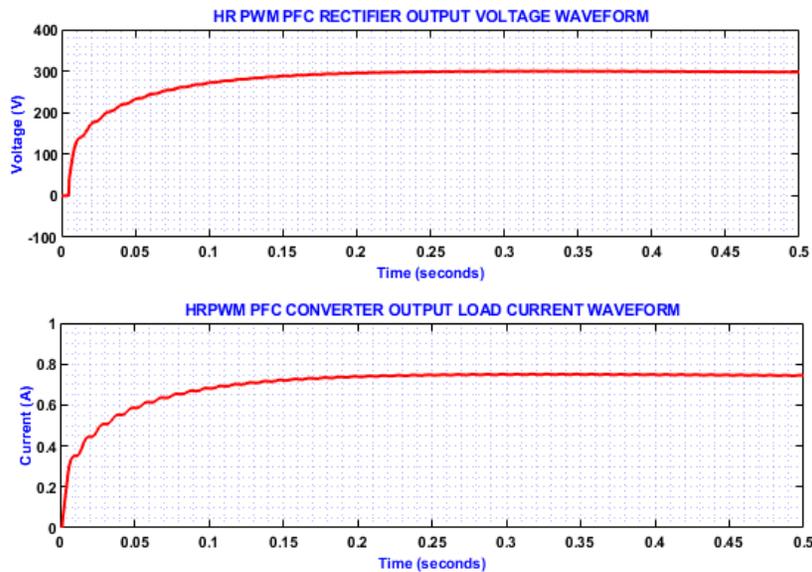


Fig. 21. Output voltage and current waveform for HR PWM PFC converter

Fig. 21 indicates the output waveform for HR PWM PFC converter, the first graph depicts the rectifier output voltage which stabilizes gradually and the second graph shows the load current output which also gradually increases and stabilizes at 0.7 A, showcasing an improved power supply. The power loss of 4.6 W is obtained from the output power of 150 W with conduction loss is nearly 65%.

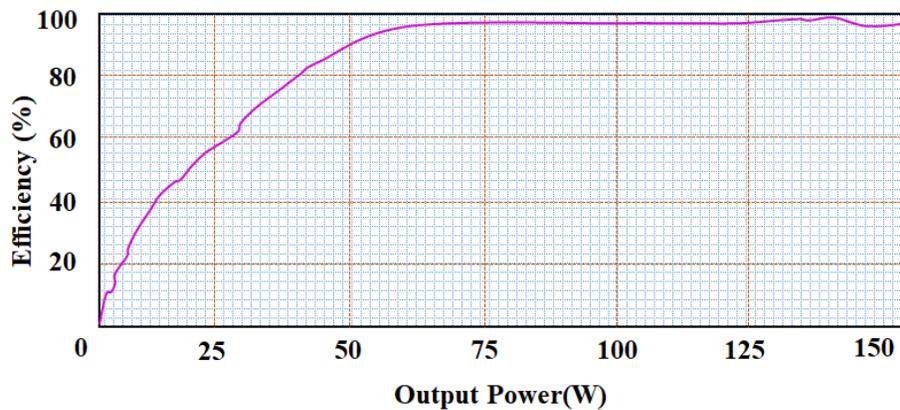


Fig. 22 Output power Vs efficiency.

An output power Vs efficiency curve is represented in Fig.22. It is concluded that the proposed converter attains the efficiency of 97%.

Table 2. Comparison of power factor correction.

| Converter  | Power Factor |
|--|--------------|
| Boost Resonant PFC converter                     | 0.83         |
| SEPIC Resonant PFC converter                     | 0.86         |
| Single Stage Resonant PFC converter              | 0.90         |
| High Frequency Resonant Bridgeless PFC converter | 1            |

Table 3. Comparison between Proposed PFC Converter with Various Conventional PFC Converters

| Configuration           | BL Buck Boost PFC converter [19] | BL SEPIC [22] | BL Luo [23] | BL Cuk [24] | Proposed BL Resonant PFC converter |
|-------------------------|----------------------------------|---------------|-------------|-------------|------------------------------------|
| Output Voltage Ripple   | High                             | High          | Low         | Low         | Low                                |
| Circuit Conduction Loss | Medium                           | High          | Low         | Low         | Low                                |
| Switch Current Stress   | High                             | High          | High        | High        | Low                                |
| Input Current Ripple    | High                             | Low           | High        | Low         | Low                                |
| Output Voltage          | Negative                         | Positive      | Positive    | Negative    | Positive                           |

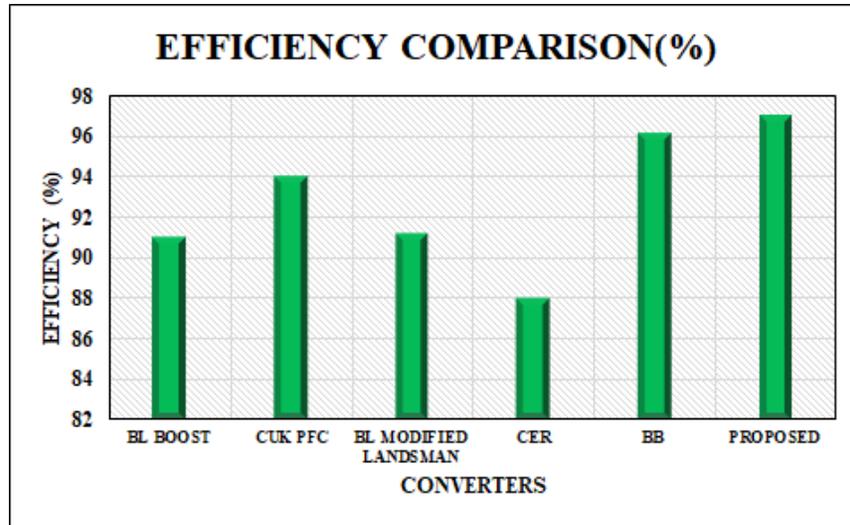


Fig. 23. Efficiency Comparison

Fig. 23 signifies the efficiency of the conventional converters with proposed converter to validate its performance efficacy, From the above chart it is evident that, the developed converter has highest efficiency of 97% while [25] BL boost, [26] BL Cuk and [27] BL modified Landsman converter attained somewhat

decreased efficacy of 91%, 94% and 91.02 % respectively. Also, the efficiency of Class E Resonant (CER) [28] and Bridgeless Boost (BB) [29] converters are 88% and 96.10%.

#### 4. Conclusion

The proposed system concludes that, by integrating High frequency resonant bridgeless PFC converter assures increased power quality, smooth AC-DC conversion with reduced power losses. In addition to this, the utilization of PWM generator with hysteresis current controller and PI controller achieves highly regulated voltage and current, thus increasing stability and reliability with enhanced performance efficacy. Therefore, the overall proposed system ensures enhanced EV charging process with increased reliability and better EV battery performance. To validate the performance efficacy of the proposed, MATLAB/Simulink implementation is utilized, which depicts that, proposed BL PFC converter attained higher efficiency of 97% with power factor unity, indicating enhances system performance with effective EV battery charging.

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Uncorrected Proof